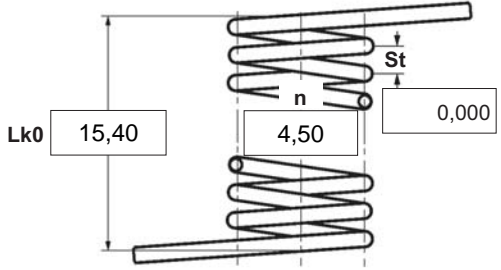


- α degree Unstressed leg position
- $\alpha 1$ degree Prestressed rotational angle
- $\alpha 2$ degree Loaded rotational angle
- αh degree Excursion
- αn degree Maximum rotational angle
- d mm Wire diameter
- Ddmin mm Min. possible mandrel diameter
- Ddmax mm Max. possible mandrel diameter
- De mm Outer coil diameter
- Di mm Inner coil diameter
- F1 N Prestressed spring force
- F2 N Loaded spring force
- Lk0 mm Length of spring body when relaxed
- LS mm Length of leg
- M1 Nmm Prestressed torque
- M2 Nmm Loaded torque
- Mn Nmm Maximum torque
- n pc. Active coils
- RH mm Distance power flow point from centre
- St mm Distance between coils (pitch)
- Weight g Weight of one spring in grammes



Spring test acc. to DIN ISO 2859/1 test level II

1 Coiling direction <input type="checkbox"/> left <input checked="" type="checkbox"/> right	5 Excursion αh <input type="text"/> degr.	12 Tolerances to DIN 2194 <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th>Grade</th> <th>Di</th> <th>Lk0</th> <th>LSH,LSR</th> <th>$\alpha, \alpha 1, \alpha 2$</th> <th>M1, M2</th> <th>Wire diameter d to DIN 2076</th> </tr> </thead> <tbody> <tr> <td>1</td> <td><input type="checkbox"/></td> <td><input type="checkbox"/></td> <td><input type="checkbox"/></td> <td><input type="checkbox"/></td> <td><input type="checkbox"/></td> <td></td> </tr> <tr> <td>2</td> <td><input checked="" type="checkbox"/></td> <td><input checked="" type="checkbox"/></td> <td><input checked="" type="checkbox"/></td> <td><input checked="" type="checkbox"/></td> <td><input checked="" type="checkbox"/></td> <td></td> </tr> <tr> <td>3</td> <td><input type="checkbox"/></td> <td><input type="checkbox"/></td> <td><input type="checkbox"/></td> <td><input type="checkbox"/></td> <td><input type="checkbox"/></td> <td><input checked="" type="checkbox"/></td> </tr> </tbody> </table>	Grade	Di	Lk0	LSH,LSR	$\alpha, \alpha 1, \alpha 2$	M1, M2	Wire diameter d to DIN 2076	1	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>		2	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>		3	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input checked="" type="checkbox"/>
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2 Form of legs tangential, straight, no bends *  *We can also supply torsion springs with any form of leg for an extra charge.	6 Stress cyc. end. N <input type="text"/>	13 Production compensation through A spring torque and the associated swing angle α <input checked="" type="checkbox"/> A spring torque and the associated swing angle and $\alpha 0$ <input type="checkbox"/> Two spring resistances and the associated swing angle α, n, d <input type="checkbox"/> α, n, Di <input type="checkbox"/>																												
3 Fixing Recumbent leg <input type="checkbox"/> Lever leg <input type="checkbox"/>	7 Stress cycle frequ. n <input type="text"/> / <input type="text"/>	8 Application temp. <input type="text"/> °C																												
4 Load <input type="checkbox"/> in winding direction <input type="checkbox"/> against winding direction	9 Material EN 10270-3-1.4310	10 Wire or rod surface <input checked="" type="checkbox"/> drawn <input type="checkbox"/> rolled <input type="checkbox"/> metal-cut																												
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